Multi-joint Robot Controller

OYes --No △Optical

Product Specifications of the Controller

Spec.	Model		TP3000	RD8800				
Hardware	Storage		SD Card (1G)	CF(1G) +SD(1G)				
	Monitor		7"TFT LCD Touch screen					
	Operation Panel		40 buttons					
	Emergency Stop		1					
	Safety Switch		2-stage switch (Standard) / 3-stage switch (Optional)					
	Communication Cord		8m (Standard) / 5,6 m (Optional)					
	Knob		For use with software functions					
	Communication Interface	USB	USB HOST(2.0)					
		EtherNET	10BASE-T/ 100BASE-TX					
		CIO	Serial Communication I/O. Expandable with LNC serial communicat I/O cards, max: 128 input points/ 128 output points.					
	Servo Interface	D1	M-II					
		D2	RTEX					
		D3	EtherCAT					
		D5	PULSE					
	Power Supply	System Power	AC 100V/240V 50/60Hz					
	rower supply	I/O Power	DC 24V(above 4A)					

Peripherals Selection

Spec.	Model		R8800 6-axis Fieldbus	RD8800 2-joint Robotic Arm	R7800 4-axis Fieldbus	R8200 6-axis Pulse	R7200 4-axis Pulse
		TRF6632	0	0	0	0	
Hardware	Main Selection	SIOA1730	0		0		
		SIO1630A					0
		SIO2500D3				0	
		ELC 2318D3		0			
	Servo Control	D1 M-II	Δ		Δ		
		D2 RTEX	RTEX 🛕		Δ		
		D3 EtherCAT	erCAT 🛕		Δ	0	
		D5 Pulse					0
Optional Accessories	Spindel Axis (Max.)	6+3	(6+3)x2	4+3	8	5
	ETS3000 IO Ex	xpansion Module	D3 only		D3 only	Δ	
	SIOA1760 IO Board		Δ		Δ	Δ	
	SIOA1700 IO Board		Δ		Δ	Δ	
	SIOA1732 IO Board		Δ		Δ	Δ	
	SIOA1632 IO	Board	-				Δ
	DAQ1550 AIO Expansion Module		D3	only	D3 only	Δ	

Peripherals Specification

Spec.	Mode	SIOA 1760 For D123	1730 For D123	SIOA 1732 For D123	SIOA 1630 For D5	SIOA 1632 For D5	SIOA 1700	ETS 3000	SIO 2500D3	DAQ 1550
Input Voltage		DC24.0±10%								
Max. Current		1.5A								
Input Point		16	21	32	21	32	22	16 (DI Module)	20	4
Input Spec.		IN point mode			Optocouple	er input ; D0	C 24V			12Bbits±10V
		NPN / PNP								12001032104
Output Point		16	24	24	24	24	16	16 (DO Module)	20	(1) 2-4 channels (2) 2 channels
Output Spec.		Relay	Transistor type output (VoL)	Transistor type output (VoL)	Relay/ Transistor type output (VoL)	Transistor type output (VoL)	Transistor type output (VoL)	Transistor type output (VoL)	Transistor type output (VoL)	(1) 16Bbits±10V DAC (2) 5V/24V PWM



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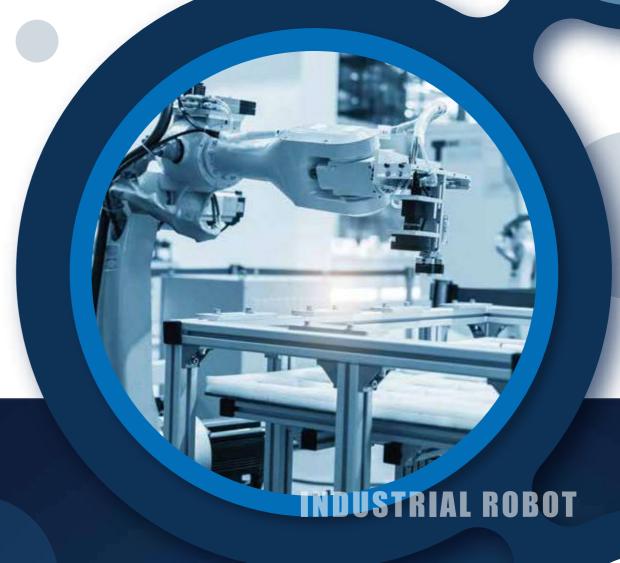
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MULTI-JOINT ROBOT

Support Various Protocols | Build-in Working Methods High Efficiency; High Performance | Intelligent Sensor







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Product Series

LNC Robotic Control Systems

Fieldbus-based robotic control systems is the foundation to implement Industry 4.0

LNC introduced a full range of fieldbus-based robot controllers for articulated and cartesian coordinate robots as well. The product series supports the most widely used communication protocols, including MECHATROLINK-II, RTEX and EtherCAT, which get customers prepared for the new era of industry 4.0.

Product Series



TP3000





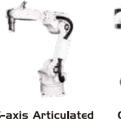








R8200 6-axis Fieldbus



6-axis Articulated

Support Robot Type



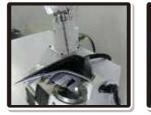


Co-robot

the additional axis, just command the coordinates of UVW. • G1 X100 Y-100 Z100

V45 F2000

- UVW: Coordinates of additional axis
- F: Speed





R8800 6-axis Fieldbus R7800 4-axis Pulse

TP3000 Teaching Box (Host integrated)

Product Peripherals

EtherCAT to DA Output (4 Channels)











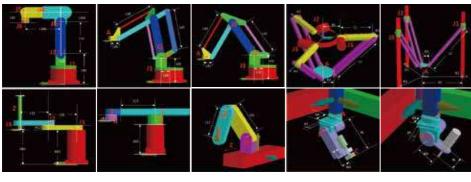


R7200 4-axis Pulse

Software Function

Support Various Types of Mechanisms

LNC 3D Builder simulation software that supports multiple forms of mechanism 3D Builder is a robot virtual control software developed by LNC. In addition to supporting the current standard mechanisms, if users have self-developed hardware or need to work with special mechanisms, they can use LNC 3D Builder for programming and motion simulation first, and then wait until all program actions and paths are confirmed. The machine performs real machine actions.



Usage

STEPI

the parameters of each

Complex motion path or high precision requirements
New or special mechanism design
Multi-device collaboration

STEP2





Software

Software Function

CAD/CAM Integration

- Built-in 2D CAM.
- The bottom layer uses G Code. Use the 3D workpiece surface processing program produced by CAM.
- Can save dedicated Robot CAM.

External Axis Control

- When commanding
- XYZABC : Coordinates of

• **G1**: Rectilinear Motion

- A0 B30 C20 U70

Support Multiple Protocol

• COM: Mainly used for pulse absolute protocol.



Modbus: Provide 485/422.



Network :

Commonly used Modbus protocol, commercially available PLC communication protocol, vision protocol, string protocol... etc.

COM Modbus, TCP Modbus, String Server. Parameters can be set directly on the screen without ini file setting.

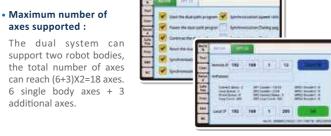
Visual

The communication string can be set on the screen, and the format of the return data has been stipulated by the standard.

axes supported:

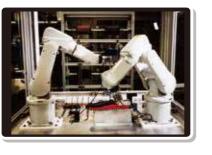
Dual-arm Robot

The dual system can support two robot bodies, the total number of axes can reach (6+3)X2=18 axes. 6 single body axes + 3 additional axes.



Dual system and dual channel It can control two independent I

at the same time, which is suitable he development of dual-arm r lual-robot collaboration or integration of robot arms and other equipment. Through a single controll o control dual channels, it can say hardware space and cost, improve da processing and calculation efficien and greatly reduce the time maintenance and troubleshooting



Expandable Ccommand Sets

• Apply to "program export" function to integrate "teaching program", " templates", "matrix" and "NC file" in the same program for operation, or according to requirement to write G code by Macro language.





Home Correction

• When under a complete organization condition, the function provides robot to reach 1mm of absolute precision





Coordinate System

• The workpiece is set up on one or more moving and rotating nlatforms for use





RM8800 series products apply

to carry industry such as

dynamic pick and place, as well as matrix stack. Digita multiaxial control (Maximun 9 axis). Industry dedicate functional setting page. Carry

procedural programmin executive function.

Spray

RS8800 series standard control-

ler of spray coating machine,

which apply to spray coating

industry, and it is divided into

fixing spray and tracking coating. IP65 level protection

is provided, which increases

the durability design such as

waterproof, Anti-shock and

dustproof. In addition, built-in

MPG is offered for meeting

requirements of easier

operation and higher safety.

Handling

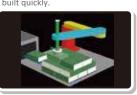
Matrix function is capable of Through setting the layout of accomplishing picking and placing templates, the stacking can be action in order to have fastsequence. built quickly.





Palletizing

Advanced Functions



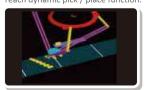


Built-in Templates

easier than ever.

Dynamic Synchrony

Apply to the dynamic follow according to the result of SmartCCD to reach dynamic pick / place function.







Synchronous Spray

Multiple spraying robots follow the the complicated process of following same conveyor belt at the same





Position Finding & Tracking Welding



Welding

RW8800 Series Welding Rob Controller, which apply welding industry. The conf includes welding art ba reach the diversity require such as dot correction, welding, spot welding, and welding bead tracking, and it supplies diversity welding machine's integration interface



Collaboration



Start processing friendly and

Reservation



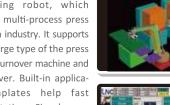


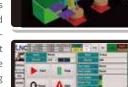
With digital welding machine, laser camer achieve a straight line, Arc tracking, position





Robotic Punching







Polishing RF8800 series of polishing

robotic controller can apply to

for further.

polishing, finishing and gluing industries. The control system emphasizes the convenience of space teaching, which offers arc space function to decrease teaching point; it provides tool / workpiece transposition calculation function for adapting the situation when robot is clamping, to reach the purpose of speedy teaching and reduce program point.

Arc Space Function



Punch

f pressing robot, which applies to multi-process press application industry. It supports the discharge type of the press machine, turnover machine and self-turnover. Built-in applicaion templates help fast mplementation. Signal page nelps grasping IO handshaking